## Chapter 4 - Motion in 2D and 3D



Generalize to 3D
Projectile Motion
Uniform Circular Motion
Relative Motion
"Never confuse motion with action."

- Benjamin Franklin

David J. Starling<br>Penn State Hazleton<br>PHYS 211 and 3D

## Generalize to 3D

Position, displacement, velocity and acceleration can be generalized to $3 D$ using vectors.

$$
x(t) \rightarrow \quad \vec{r}(t)=x(t) \hat{i}+y(t) \hat{j}+z(t) \hat{k}
$$

## Generalize to 3D

Projectile Motion
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## Generalize to 3D

Chapter 4 - Motion in 2D and 3D

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x(t) & \rightarrow & \vec{r}(t) & =x(t) \hat{i}+y(t) \hat{j}+z(t) \hat{k} \\
\Delta x & & \Delta \vec{r} & =\vec{r}_{2}(t)-\vec{r}_{1}(t)
\end{aligned}
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v_{\text {avg }}(t) & \rightarrow & \vec{v}_{\text {avg }}(t) & =\frac{\Delta \vec{r}}{\Delta t}
\end{aligned}
$$

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v(t) & & \vec{v}(t) & =\frac{d \vec{r}}{d t}=v_{x}(t) \hat{i}+v_{y}(t) \hat{j}+v_{z}(t) \hat{k}
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a_{\text {avg }}(t) & \rightarrow & \vec{a}_{\text {avg }}(t) & =\frac{\Delta \vec{v}}{\Delta t}
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## Generalize to 3D

Position, displacement, velocity and acceleration can be generalized to 3D using vectors.

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\end{aligned}
$$

## Generalize to 3D

We can also generalize two of our constant acceleration equations.

## Generalize to 3D

Projectile Motion
Uniform Circular Motion
Relative Motion

$$
\begin{array}{ll}
v(t)=v_{0}+a t & \rightarrow \vec{v}(t)=\vec{v}_{0}+\vec{a} t \\
x(t)=x_{0}+v_{0} t+\frac{1}{2} a t^{2} & \rightarrow \vec{r}(t)=\vec{r}_{0}+\vec{v}_{0} t+\frac{1}{2} \vec{a} t^{2}
\end{array}
$$

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x(t)=x_{0}+v_{0} t+\frac{1}{2} a t^{2} & \rightarrow \vec{r}(t)=\vec{r}_{0}+\vec{v}_{0} t+\frac{1}{2} \vec{a} t^{2} \\
& \rightarrow v_{x}^{2}=v_{0, x}^{2}+2 a_{x} \Delta x \\
& \rightarrow v_{y}^{2}=v_{0, y}^{2}+2 a_{y} \Delta y \\
& \rightarrow v_{z}^{2}=v_{0, z}^{2}+2 a_{z} \Delta z
\end{array}
$$

## Objectives (Ch 4)

## Lecture Question 4.1

When an object is thrown (ignoring air drag), after it has left the thrower's hand,
(a) $v_{x}$ and $v_{y}$ are constant.
(b) $v_{x}$ and $v_{y}$ change with time.
(c) $v_{x}$ changes with time but $v_{y}$ is constant.
(d) $v_{x}$ is constant but $v_{y}$ changes with time.

## Projectile Motion

Projectile motion is a very common example of $2 D$ motion where objects move under the influence of gravity.


## Projectile Motion

Projectile motion is a very common example of $2 D$ motion where objects move under the influence of gravity.


This ball is also rotating - we'll get to that later (Ch 10).

## Projectile Motion

Chapter 4 - Motion in 2D and 3D

In projectile motion, the acceleration in the horizontal direction is $0 \mathrm{~m} / \mathrm{s}^{2}$.

Generalize to 3D<br>Projectile Motion<br>Uniform Circular Motion<br>Relative Motion



## Projectile Motion

Chapter 4 - Motion in 2D and 3D

In projectile motion, the acceleration in the horizontal direction is $0 \mathrm{~m} / \mathrm{s}^{2}$.

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If we pick $+x$ as right, $a_{x}=0 \mathrm{~m} / \mathrm{s}^{2}$.

## Projectile Motion

Chapter 4 - Motion in 2D and 3D

In projectile motion, the acceleration in the vertical direction is $g=9.81 \mathrm{~m} / \mathrm{s}^{2}$.

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## Projectile Motion

Chapter 4 - Motion in 2D and 3D

In projectile motion, the acceleration in the vertical direction is $g=9.81 \mathrm{~m} / \mathrm{s}^{2}$.

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If we pick $+y$ as up, $a_{y}=-9.8 \mathrm{~m} / \mathrm{s}^{2}$.

## Projectile Motion

In projectile motion, the horizontal and vertical motion are independent of each other.

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## Projectile Motion

In projectile motion, the horizontal and vertical motion are independent of each other.

## Generalize to 3D

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We use our standard equations:

$$
\begin{aligned}
& x(t)=x_{0}+v_{0, x} t+\frac{1}{2} a_{x} t^{2} \\
& y(t)=y_{0}+v_{0, y} t+\frac{1}{2} a_{y} t^{2}
\end{aligned}
$$

## Projectile Motion

## Lecture Question 4.2

A bullet is aimed at a target on the wall a distance $L$ away from the firing position and the bullet strikes the wall a distance $\Delta y$ below the mark. If the distance $L$ was half as large, and the bullet had the same initial velocity, how would $\Delta y$ change?

(a) $\Delta y \rightarrow 2 \Delta y$
(b) $\Delta y \rightarrow 4 \Delta y$
(c) $\Delta y \rightarrow \Delta y / 2$
(d) $\Delta y \rightarrow \Delta y / 4$
(e) Need more information.

## Uniform Circular Motion

An object is in uniform circular motion when its speed is constant and it travels in a circle.

## Generalize to 3D

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Relative Motion

## Uniform Circular Motion

An object moving in a circle experiences acceleration (even if it's moving at constant speed!).

Chapter 4 - Motion in 2D and 3D

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## Uniform Circular Motion

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## Uniform Circular Motion

An object moving in a circle experiences acceleration (even if it's moving at constant speed!).

## Uniform Circular Motion

For uniform circular motion, we can find the centripetal acceleration $a_{r}$ using geometry and calculus.

Chapter 4 - Motion in 2D and 3D

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## Uniform Circular Motion

For uniform circular motion, we can find the centripetal acceleration $a_{r}$ using geometry and calculus.




## Generalize to 3D

Projectile Motion
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Relative Motion

## Uniform Circular Motion

For uniform circular motion, we can find the centripetal acceleration $a_{r}$ using geometry and calculus.




$$
\vec{v}=v_{x} \hat{i}+v_{y} \hat{j}
$$

Generalize to 3D
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Relative Motion

## Uniform Circular Motion

For uniform circular motion, we can find the centripetal acceleration $a_{r}$ using geometry and calculus.




$$
\begin{aligned}
\vec{v} & =v_{x} \hat{i}+v_{y} \hat{j} \\
& =[-v \sin (\theta)] \hat{i}+[v \cos (\theta)] \hat{j}
\end{aligned}
$$

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## Uniform Circular Motion

For uniform circular motion, we can find the centripetal acceleration $a_{r}$ using geometry and calculus.

## Generalize to 3D

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## Uniform Circular Motion

For uniform circular motion, we can find the centripetal acceleration $a_{r}$ using geometry and calculus.

Generalize to 3D
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$$
\begin{aligned}
\vec{v} & =v_{x} \hat{i}+v_{y} \hat{j} \\
& =[-v \sin (\theta)] \hat{i}+[v \cos (\theta)] \hat{j} \\
& =\left(-\frac{v y}{r}\right) \hat{i}+\left(\frac{v x}{r}\right) \hat{j} \\
\vec{a} & =\frac{d \vec{v}}{d t}
\end{aligned}
$$

## Uniform Circular Motion





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## Uniform Circular Motion





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## Uniform Circular Motion

Chapter 4 - Motion in 2D
Chapter 4 - Motio
and 3D




Generalize to 3D
Projectile Motion
Uniform Circular Motion
Relative Motion

$$
\begin{aligned}
\vec{v} & =\frac{v}{r}(-y \hat{i}+x \hat{j}) \\
\vec{a} & =\frac{d \vec{v}}{d t}=\frac{v}{r}\left(-v_{y} \hat{i}+v_{x} \hat{j}\right) \\
a & =\sqrt{a_{x}^{2}+a_{y}^{2}}
\end{aligned}
$$

## Uniform Circular Motion




Chapter 4 - Motion in 2D and 3D

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\vec{a} & =\frac{d \vec{v}}{d t}=\frac{v}{r}\left(-v_{y} \hat{i}+v_{x} \hat{j}\right) \\
a & =\sqrt{a_{x}^{2}+a_{y}^{2}} \\
& =\frac{v}{r} \sqrt{v_{y}^{2}+v_{x}^{2}}
\end{aligned}
$$

## Uniform Circular Motion




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\begin{aligned}
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\vec{a} & =\frac{d \vec{v}}{d t}=\frac{v}{r}\left(-v_{y} \hat{i}+v_{x} \hat{j}\right) \\
a & =\sqrt{a_{x}^{2}+a_{y}^{2}} \\
& =\frac{v}{r} \sqrt{v_{y}^{2}+v_{x}^{2}} \\
a & =\frac{v^{2}}{r} \text { (uniform circular motion) }
\end{aligned}
$$

## Uniform Circular Motion

## Lecture Question 4.3

A steel ball is whirled on the end of a chain in a horizontal

Projectile Motion
Uniform Circular Motion
Relative Motion
(a) Centripetal acceleration increases.
(b) Centripetal acceleration decrease.
(c) Centripetal acceleration stays the same.
(d) Not enough information.

## Relative Motion

The velocity of an object depends on the reference frame from which it is measured.


## Relative Motion

The velocity of an object depends on the reference frame from which it is measured.

- frame A (Alice) is stationary
- frame B (Bob) moves with some constant velocity
- object P (Parakeet) is measured


## Relative Motion



- $x_{B A}$ : position of Bob relative to Alice
- $x_{P B}$ : position of Parakeet relative to Bob
- $x_{P A}$ : position of Parakeet relative to Alice


## Relative Motion



- $x_{B A}$ : position of Bob relative to Alice
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$$
x_{P A}=x_{P B}+x_{B A}
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- $x_{P A}$ : position of Parakeet relative to Alice

$$
\begin{aligned}
x_{P A} & =x_{P B}+x_{B A} \\
v_{P A} & =v_{P B}+v_{B A}
\end{aligned}
$$

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## Relative Motion



## Generalize to 3D

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- $x_{P A}$ : position of Parakeet relative to Alice

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\begin{aligned}
x_{P A} & =x_{P B}+x_{B A} \\
v_{P A} & =v_{P B}+v_{B A} \\
a_{P A} & =a_{P B}+a_{B A}
\end{aligned}
$$

## Relative Motion



Generalize to 3D
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- $\vec{r}_{B A}$ : position of Bob relative to Alice
- $\vec{r}_{P B}$ : position of Parakeet relative to Bob
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$$
\vec{r}_{P A}=\vec{r}_{P B}+\vec{r}_{B A}
$$

## Relative Motion



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- $\vec{r}_{P A}$ : position of Parakeet relative to Alice

$$
\begin{aligned}
\vec{r}_{P A} & =\vec{r}_{P B}+\vec{r}_{B A} \\
\vec{v}_{P A} & =\vec{v}_{P B}+\vec{v}_{B A}
\end{aligned}
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## Relative Motion



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- $\vec{r}_{P A}$ : position of Parakeet relative to Alice

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\begin{aligned}
\vec{r}_{P A} & =\vec{r}_{P B}+\vec{r}_{B A} \\
\vec{v}_{P A} & =\vec{v}_{P B}+\vec{v}_{B A} \\
\vec{a}_{P A} & =\vec{a}_{P B}+\vec{a}_{B A}
\end{aligned}
$$

